# INSTALLATION GUIDELINE FR－F 740－00023 to 12120－EC FR－F 746－00023 to 01160－EC 

Thank you for choosing this Mitsubishi Inverter．Please read through this Instruction Manual and the enclosed CD ROM to operate this inverter correctly－The enclosed CD ROM contains the Installation Guideline in additional languages．
－Die CD－ROM enthält die deutsche Installationsbeschreibung．
－II CD－ROM incluso contiene la guida di riferimento dell＇installazione in lingua italiana．
－Le CD－ROM ci－joint contient cette documentation en français．
－EI CD－ROM incluido contiene la pauta de la instalación en lengua española．
－Приложенный CD－ROM содержит инструкцию по инсталяции на дополнительных языках．
Do not use this product until you have a full knowledge of the equipment，the safety information and theinstructions．
Please forward this manual and the CD ROM to the end user．
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## 4. For Maximum Safety

- Mitsubishi transistorized inverters are not designed or manufactured to be used in equipment or systems in situations that can affect or endanger human life.
- When considering this product for operation in special applications such as machinery or systems used in passenger transportation, medical, aerospace, atomic power, electric power, or submarine repeating applications, please contact your nearest Mitsubishi sales representative.
- Although this product was manufactured under conditions of strict quality control, you are strongly advised to install safety devices to prevent serious accidents when it is used in facilities where breakdowns of the product are likely to cause a serious accident.
- Please do not use this product for loads other than three-phase induction motors.


## This section is specifically about safety matters

Do not attempt to install, operate, maintain or inspect the inverter until you have read through this Installation Guideline and appended documents carefully and can use the equipment correctly. Do not use the inverter until you have a full knowledge of the equipment, safety information and instructions. In this Installation Guideline, the safety instruction levels are classified into "WARNING" and "CAUTION".

## A WARNING $\triangle$ CAUTION

Assumes that incorrect handling may cause hazardous conditions, resulting in death or severe injury.
Assumes that incorrect handling may cause hazardous conditions, resulting in medium or slight injury, or may cause physical damage only.

Note that even the $\triangle$ CAUTION level may lead to a serious consequence according to conditions. Please follow strictly the instructions of both levels because they are important to personnel safety.

## Electric Shock Prevention

## AWARNING

- While power is on or when the inverter is running, do not open the front cover. Otherwise you may get an electric shock.
- Do not run the inverter with the front cover removed. Otherwise, you may access the exposed high-voltage terminals or the charging part of the circuitry and get an electric shock.
- Even if power is off, do not remove the front cover except for wiring or periodic inspection.You may access the charged inverter circuits and get an electric shock.
- Before starting wiring or inspection, check to make sure that the operation panel indicator is off, wait for at least 10 minutes after the power supply has been switched off, and check that there are no residual voltage using a tester or the like. The capacitor is charged with high voltage for some time after power off and it is dangerous.
- This inverter must be earthed. Earthing must conform to the requirements of national and local safety regulations and electrical codes (JIS, NEC section 250, IEC 536 class 1 and other applicable standards)
- Any person who is involved in the wiring or inspection of this equipment should be fully competent to do the work.
- Always install the inverter before wiring. Otherwise, you may get an electric shock or be injured.
- Perform setting dial and key operations with dry hands to prevent an electric shock. Otherwise you may get an electric shock.
- Do not subject the cables to scratches, excessive stress, heavy loads or pinching. Otherwise you may get an electric shock.
- Do not replace the cooling fan while power is on. It is dangerous to replace the cooling fan while power is on.
- Do not touch the printed circuit board with wet hands. You may get an electric shock.


## Fire Prevention

## ACAUTION

- Mount the inverter to incombustible material. Mounting it to or near combustible material can cause a fire.
- If the inverter has become faulty, switch off the inverter power.

A continuous flow of large current could cause a fire.

- Do not connect a resistor directly to the DC terminals P, N. This could cause a fire and destroy the inverter. The surface temperature of braking resistors can far exceed $100^{\circ} \mathrm{C}$ for brief periods. Make sure that there is adequate protection against accidental contact and a safe distance is maintained to other units and system parts.


## Injury Prevention

- CAUTION
- Apply only the voltage specified in the instruction manual to each terminal. Otherwise, burst, damage, etc. may occur.
- Ensure that the cables are connected to the correct terminals. Otherwise, burst, damage, etc. may occur.
- Always make sure that polarity is correct to prevent damage, etc. Otherwise, burst, damage, etc. may occur.
- While power is on or for some time after power-off, do not touch the inverter as it is hot and you may get burnt.

Additional Instructions
Also note the following points to prevent an accidental failure, injury, electric shock, etc.

## Transportation and installation

## ACAUTION

- When carrying products, use correct lifting gear to prevent injury.
- Do not stack the inverter boxes higher than the number recommended.
- Ensure that installation position and material can withstand the weight of the inverter. Install according to the information in the instruction manual.
- Do not install or operate the inverter if it is damaged or has parts missing. This can result in breakdowns.
- When carrying the inverter, do not hold it by the front cover or setting dial; it may fall off or fail.
- Do not stand or rest heavy objects on the product.
- Check the inverter mounting orientation is correct.
- Prevent other conductive bodies such as screws and metal fragments or other flammable substance such as oil from entering the inverter.
- As the inverter is a precision instrument, do not drop or subject it to impact.
- Use the inverter under the following environmental conditions. Otherwise, the inverter may be damaged.

| Operating condition | FR-F 740 | FR-F 746 |
| :--- | :--- | :--- |
| Ambient temperature | $-10^{\circ} \mathrm{C}$ to $+40 /+50^{\circ} \mathrm{C}$ (non-freezing) | $-10^{\circ} \mathrm{C}$ to $+30 /+40^{\circ} \mathrm{C}$ (non-freezing) |
|  | The maximum temperature depends on the setting of the Pr. 570. |  |
| Ambient humidity | $90 \%$ RH or less (non-condensing) |  |
| Storage temperature | $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}{ }^{1}$ |  |
| Atmosphere | Indoors (free from corrosive gas, flammable gas, oil mist, dust and dirt) |  |
| Altitude | Maximum 1000 m above sea level for standard operation. After that derate by 3\% for <br> every extra 500m up to $2500 \mathrm{~m}(92 \%)$ |  |
| Vibration | $5.9 \mathrm{~m} / \mathrm{s}^{2(2)}$ or less (conforming to JIS C 60068-2-6) |  |

(1) Temperature applicable for a short time, e.g. in transit.
(2) $2.9 \mathrm{~m} / \mathrm{s}^{2}$ or less for the 04320 or more.
$\square$
$\triangle C A U T I O N$

- Do not install assemblies or components (e. g. power factor correction capacitors) on the inverter output side, which are not approved from Mitsubishi.
- The direction of rotation of the motor corresponds to the direction of rotation commands (STF/STR) only if the phase sequence (U, V, W) is maintained.


## Test operation and adjustment

## $\triangle C A U T I O N$

- Before starting operation, confirm and adjust the parameters. A failure to do so may cause some machines to make unexpected motions.


## Operation

| AWARNING |
| :--- | :--- |
| - When you have chosen the retry function, stay away from the equipment as it will restart suddenly after an alarm stop. |
| - The (sise $)$ key is valid only when the appropriate function setting has been made. Prepare an emergency stop switch separately. |
| - Make sure that the start signal is off before resetting the inverter alarm. A failure to do so may restart the motor suddenly. |
| - The inverter can be statrad and stopped via the serial port communications link or the field bus. However, please note that depending |
| on the settings of the communications parameters it may not be possible to stop the system via these connections if there is an error |
| in the communications system or the data line. In configurations like this it is thus essential to install additional safety hardware that |
| makes it possible to stop the system in an emergency (e.g. controller inhibibi via control signal, external motor contactor etc). Clear and |
| unambiguous warnings about this must be posted on site for the operating and service staff. |
| - The load used should be a three-phase induction motor only. Connection of any other electrical equipment to the inverter output may |
| damage the inverter as well as the equipment. |
| - Do not modify the equipment. |
| - Do not perform parts removal which is not instructed in this manual. Doing so may lead to fault or damage of the inverter. |

## $\triangle C A U T I O N$

- The electronic thermal relay function does not guarantee protection of the motor from overheating.
- Do not use a magnetic contactor on the inverter input for frequent starting/stopping of the inverter.
- Use a noise filter to reduce the effect of electromagnetic interference and follow the accepted EMC procedures for proper installation of frequency inverters. Otherwise nearby electronic equipment may be affected.
- Take appropriate measures regarding harmonics. Otherwise this can endanger compensation systems or overload generators.
- Use a motor designed for inverter operation. (The stress for motor windings is bigger than in line power supply).
- When parameter clear or all clear is performed, set again the required parameters before starting operations. Each parameter returns to the initial value.
- The inverter can be easily set for high-speed operation. Before changing its setting, fully examine the performances of the motor and machine.
- The DC braking function of the frequency inverter is not designed to continuously hold a load. Use an electro-mechanical holding brake on the motor for this purpose.
- Before running an inverter which had been stored for a long period, always perform inspection and test operation.
- For prevention of damage due to static electricity, touch nearby metal before touching this product to eliminate static electricity from your body.
Emergency stop


## ©CAUTION

- Provide a safety backup such as an emergency brake which will prevent the machine and equipment from hazardous conditions if the inverter fails.
- When the breaker on the inverter primary side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter, etc. Identify the cause of the trip, then remove the cause and power on the breaker.
- When the protective function is activated (i. e. the frequency inverter switches off with an error message), take the corresponding corrective action as described in the inverter manual, then reset the inverter, and resume operation.

Maintenance, inspection and parts replacement

| $\bullet$ Do not carry out a megger (insulation resistance) test on the control circuit of the inverter. |
| :--- |

Disposing of the inverter

|  | さCAUTION |
| :--- | :--- |
| $\bullet$ Treat as industrial waste. |  |

## General instructions

Many of the diagrams and drawings in instruction manuals show the inverter without a cover, or partially open. Never run the inverter in this status. Always replace the cover and follow instruction manuals when operating the inverter.

## 1 INSTALLATION AND INSTRUCTIONS

### 1.1 Inverter Type



## Capacity plate example

$$
\begin{array}{rl|l|}
\hline \text { Capacity plate } & \begin{array}{ll}
\text { FR-F740-00126-EC } \times \times \times \times x \times \\
& \text { Inverter type }
\end{array} & \text { Serial number }
\end{array}
$$

### 1.2 Installation of the inverter



## Note

- It is not necessary to leave spaces on both sides of the inverter FR-F 746.


### 1.3 General Precaution

The bus capacitor discharge time is 10 minutes. Before starting wiring or inspection, switch power off, wait for more than 10 minutes, and check for residual voltage between terminal $\mathrm{P} /+$ and $\mathrm{N} /-$ with a meter etc., to avoid a hazard of electrical shock.

### 1.4 Environment

Before installation, check that the environment meets following specifications.

| Ambient temperature | $-10^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}\left(+40^{\circ} \mathrm{C}\right.$ for FR-F 746) (non-freezing) for selected overload capability $150 \%(\operatorname{Pr} 570=0)$ <br> $-10^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}\left(+30^{\circ} \mathrm{C}\right.$ for FR-F 746) (non-freezing) for selected overload capability 120\% (Pr. $570=1$ ) |  |
| :---: | :---: | :---: |
| Ambient humidity | 90\% RH or less (non-condensing) |  |
| Storage temperature | $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ |  |
| Ambience | Indoors (No corrosive and flammable gases, oil mist, dust and dirt) |  |
| Altitude, vibration | Below $1000 \mathrm{~m}, 5.9 \mathrm{~m} / \mathrm{s}^{2}{ }^{1}$ or less |  |

(1) $2.9 \mathrm{~m} / \mathrm{s}^{2}$ or less for the 04320 or more.

## CAUTION

- Install the inverter on a strong surface securely and vertically with bolts.
- Leave enough clearances and take cooling measures.
- Avoid places where the inverter is subjected to direct sunlight, high temperature and high humidity.
- Install the inverter on a non-combustible surface.


## 2 OUTLINE DRAWING


(Unit: mm)

|  | Inverter Type | W | W1 | W2 | W3 | H | H1 | D | d |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | FR-F 740-00023-00126-EC | 150 | 125 | - | - | 260 | 245 | 140 | 6 |
|  | FR-F 740-00170/00250-EC | 220 | 195 | - | - | 260 | 245 | 170 | 6 |
|  | FR-F 740-00310/00380-EC | 220 | 195 | - | - | 300 | 285 | 190 | 6 |
|  | FR-F 740-00470/00620-EC | 250 | 230 | - | - | 400 | 380 | 190 | 10 |
|  | FR-F 740-00770-EC | 325 | 270 | - | - | 550 | 530 | 195 | 10 |
|  | FR-F 740-00930/01160-EC | 435 | 380 | - | - | 550 | 525 | 250 | 12 |
|  | FR-F 740-01800-EC | 465 | 380 | - | - | 550 | 525 | 250 | 12 |
|  | FR-F 740-02160/02600-EC | 465 | 400 | - | - | 620 | 595 | 300 | 12 |
|  | FR-F 740-03250/03610-EC | 465 | 400 | - | - | 740 | 715 | 360 | 12 |
|  | FR-F 740-04320/04810-EC | 498 | 400 | 200 | - | 1010 | 985 | 380 | 12 |
|  | FR-F 740-05470-06830-EC | 680 | 600 | 300 | - | 1010 | 984 | 380 | 12 |
|  | FR-F 740-07700/08660-EC | 790 | 630 | 315 | - | 1330 | 1300 | 440 | 12 |
|  | FR-F 740-09629-12120-EC | 950 | 900 | - | 300 | 1580 | 1550 | 440 | 12 |
|  | FR-F 746-00023-00126-EC | 249 | 180 | - | - | 395 | 380 | 210 | 7 |
|  | FR-F 746-00170/00250-EC | 319 | 255 | - | - | 395 | 380 | 240 | 7 |
|  | FR-F 746-00310/00380-EC | 319 | 258 | - | - | 445 | 425 | 260 | 10 |
|  | FR-F 746-00470/00620-EC | 354 | 312 | - | - | 560 | 540 | 260 | 10 |
|  | FR-F 746-00770-EC | 360 | 300 | - | - | 590 | 570 | 265 | 10 |
|  | FR-F 746-00930/01160-EC | 471 | 411 | - | - | 660 | 635 | 320 | 12 |

## 3 WIRING



## CAUTION

- To prevent a malfunction due to noise, keep the signal cables more than 10 cm away from the power cables.
- After wiring, wire offcuts must not be left in the inverter.

Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean.
When drilling mounting holes in a control box etc., take care not to allow chips and other foreign matter to enter the inverter.

### 3.1 Main circuit terminal

### 3.1.1 Terminal layout and wiring

|  |  |
| :---: | :---: |
| FR-F 740/746-00310, 00380-EC |  |
|  |  |


| FR-F 740-03250, 03610-EC <br> Screw size M12 <br> (for Option) | FR-F 740-04320, 04810-EC <br> Screw size M12 <br> (for Option) |
| :---: | :---: |
| FR-F 740-05470 to 12120-EC |  |

CAUTION

- The power supply cables must be connected to R/L1, S/L2, T/L3. Never connect the power cable to the U, V, W, of the inverter. Doing so will damaged the inverter. (Phase sequence needs not to be matched.)
- Connect the motor to U, V, W. At this time turning on the forward rotation switch (signal) rotates the motor in the counterclockwise direction when viewed from the motor shaft.


### 3.2 Wiring fundamentals

### 3.2.1 Cable size

Select the recommended cable size to ensure that a voltage drop will be $2 \%$ max.
If the wiring distance is long between the inverter and motor, a main circuit cable voltage drop will cause the motor torque to decrease especially at the output of a low frequency.
The following table indicates a selection example for the wiring length of 20 m .
400 V class (when input power supply is 440 V based on the rated current for $110 \%$ overload for 1 minute)

| Applicable Inverter Type | Terminal Screw Size *4 | Tightening Torque [ $\mathrm{N} \cdot \mathrm{m}$ ] | Crimping Terminal |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | R/L1, S/L2, T/L3 | U, V, W |
| FR-F 740/746-00023-00083-EC | M4 | 1.5 | 2-4 | 2-4 |
| FR-F 740/746-00126-EC | M4 | 1.5 | 2-4 | 2-4 |
| FR-F 740/746-00170-EC | M4 | 1.5 | 5.5-4 | 5.5-4 |
| FR-F 740/746-00250-EC | M4 | 1.5 | 5.5-4 | 5.5-4 |
| FR-F 740/746-00310-EC | M5 | 2.5 | 8-5 | 8-5 |
| FR-F 740/746-00380-EC | M5 | 2.5 | 14-5 | 8-5 |
| FR-F 740/746-00470-EC | M6 | 4.4 | 14-6 | 14-6 |
| FR-F 740/746-00620-EC | M6 | 4.4 | 22-6 | 22-6 |
| FR-F 740/746-00770-EC | M6 | 4.4 | 22-6 | 22-6 |
| FR-F 740/746-00930-EC | M8 | 7.8 | 38-8 | 38-8 |
| FR-F 740/746-01160-EC | M8 | 7.8 | 60-8 | 60-8 |
| FR-F 740-01800-EC | M8 | 7.8 | 60-8 | 60-8 |
| FR-F 740-02160-EC | M10 | 14.7 | 100-10 | 100-10 |
| FR-F 740-02600-EC | M10 | 14.7 | 100-10 | 150-10 |
| FR-F 740-03250-EC | M10 | 14.7 | 150-10 | 150-10 |
| FR-F 740-03610-EC | M10 | 14.7 | 150-10 | 150-10 |
| FR-F 740-04320-EC | M12/M10 | 24.5 | 100-12 | 100-12 |
| FR-F 740-04810-EC | M12/M10 | 24.5 | 100-12 | 100-12 |
| FR-F 740-05470-EC | M12/M10 | 24.5 | 150-12 | 150-12 |
| FR-F 740-06100-EC | M12/M10 | 24.5 | 150-12 | 150-12 |
| FR-F 740-06830-EC | M12/M10 | 24.5 | 200-12 | 200-12 |
| FR-F 740-07700-EC | M12/M10 | 24.5 | C2-200 | C2-200 |
| FR-F 740-08660-EC | M12/M10 | 24.5 | C2-250 | C2-250 |
| FR-F 740-09620-EC | M12/M10 | 24.5 | C2-250 | C2-250 |
| FR-F 740-10940-EC | M12/M10 | 24.5 | C2-200 | C2-200 |
| FR-F 740-12120-EC | M12/M10 | 24.5 | C2-200 | C2-200 |


| Applicable Inverter Type | Cable Sizes |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | HIV, etc. [mm ${ }^{2}{ }^{\text {*1 }}$ |  |  | AWG *2 |  | PVC, etc. [mm ${ }^{2}{ }^{\text {*3 }}$ |  |  |
|  | $\begin{gathered} \text { R/L1, S/L2, } \\ \text { T/L3 } \end{gathered}$ | U, V, W | Earth Cable Gauge | R/L1, S/L2, T/L3 | U, V, W | $\begin{gathered} \text { R/L1, S/L2, } \\ \text { T/L3 } \end{gathered}$ | U, V, W | Earth Cable Gauge |
| FR-F 740/746-00023-00083-EC | 2 | 2 | 2 | 14 | 14 | 2.5 | 2.5 | 2.5 |
| FR-F 740/746-00126-EC | 2 | 2 | 3.5 | 12 | 14 | 2.5 | 2.5 | 4 |
| FR-F 740/746-00170-EC | 3.5 | 3.5 | 3.5 | 12 | 12 | 4 | 4 | 4 |
| FR-F 740/746-00250-EC | 5.5 | 5.5 | 8 | 10 | 10 | 6 | 6 | 10 |
| FR-F 740/746-00310-EC | 8 | 8 | 8 | 8 | 8 | 10 | 10 | 10 |
| FR-F 740/746-00380-EC | 14 | 8 | 14 | 6 | 8 | 16 | 10 | 16 |
| FR-F 740/746-00470-EC | 14 | 14 | 14 | 6 | 6 | 16 | 16 | 16 |
| FR-F 740/746-00620-EC | 22 | 22 | 14 | 4 | 4 | 25 | 25 | 16 |
| FR-F 740/746-00770-EC | 22 | 22 | 14 | 4 | 4 | 25 | 25 | 16 |
| FR-F 740/746-00930-EC | 38 | 38 | 22 | 1 | 2 | 50 | 50 | 25 |
| FR-F 740/746-01160-EC | 60 | 60 | 22 | 1/0 | 1/0 | 50 | 50 | 25 |
| FR-F 740-01800-EC | 60 | 60 | 38 | 1/0 | 1/0 | 50 | 50 | 25 |
| FR-F 740-02160-EC | 80 | 80 | 38 | 3/0 | 3/0 | 70 | 70 | 35 |
| FR-F 740-02600-EC | 100 | 125 | 38 | 4/0 | 4/0 | 95 | 95 | 50 |
| FR-F 740-03250-EC | 125 | 125 | 38 | 250 | 250 | 120 | 120 | 70 |
| FR-F 740-03610-EC | 150 | 150 | 38 | 300 | 300 | 150 | 150 | 95 |
| FR-F 740-04320-EC | $2 \times 100$ | $2 \times 100$ | 38 | $2 \times 4 / 0$ | $2 \times 4 / 0$ | $2 \times 95$ | $2 \times 95$ | 95 |
| FR-F 740-04810-EC | $2 \times 100$ | $2 \times 100$ | 38 | $2 \times 4 / 0$ | $2 \times 4 / 0$ | $2 \times 95$ | $2 \times 95$ | 95 |
| FR-F 740-05470-EC | $2 \times 125$ | $2 \times 125$ | 38 | $2 \times 250$ | $2 \times 250$ | $2 \times 120$ | $2 \times 120$ | 120 |
| FR-F 740-06100-EC | $2 \times 150$ | $2 \times 150$ | 38 | $2 \times 300$ | $2 \times 300$ | $2 \times 150$ | $2 \times 150$ | 150 |
| FR-F 740-06830-EC | $2 \times 200$ | $2 \times 200$ | 60 | $2 \times 350$ | $2 \times 350$ | $2 \times 185$ | $2 \times 185$ | $2 \times 95$ |
| FR-F 740-07700-EC | $2 \times 200$ | $2 \times 200$ | 60 | $2 \times 400$ | $2 \times 400$ | $2 \times 185$ | $2 \times 185$ | $2 \times 95$ |
| FR-F 740-08660-EC | $2 \times 250$ | $2 \times 250$ | 60 | $2 \times 500$ | $2 \times 500$ | $2 \times 240$ | $2 \times 240$ | $2 \times 120$ |
| FR-F 740-09620-EC | $2 \times 250$ | $2 \times 250$ | 100 | $2 \times 500$ | $2 \times 500$ | $2 \times 240$ | $2 \times 240$ | $2 \times 120$ |
| FR-F 740-10940-EC | $3 \times 200$ | $3 \times 200$ | 100 | $3 \times 350$ | $3 \times 350$ | $3 \times 185$ | $3 \times 185$ | $2 \times 150$ |
| FR-F 740-12120-EC | $3 \times 200$ | $3 \times 200$ | 100 | $3 \times 400$ | $3 \times 400$ | $3 \times 185$ | $3 \times 185$ | $2 \times 150$ |

${ }^{* 1}$ For the 01160 or less, the recommended cable size is that of the HIV cable ( 600 V class 2 vinyl-insulated cable) with continuous maximum permissible temperature of $75^{\circ} \mathrm{C}$. Assumes that the ambient temperature is $50^{\circ} \mathrm{C}$ or less and the wiring distance is 20 m or less.
For the 01800 or more, the recommended cable size is that of LMFC (heat resistant flexible cross-linked polyethylene insulated cable) with continuous maximum permissible temperature of $90^{\circ} \mathrm{C}$. Assumes that the ambient temperature is $50^{\circ} \mathrm{C}$ or less and wiring is performed in an enclosure.
${ }^{* 2}$ For the 00930 or less, the recommended cable size is that of the THHW cable with continuous maximum permissible temperature of $75^{\circ} \mathrm{C}$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}$ or less and the wiring distance is 20 m or less.
For the 01160 or more, the recommended cable size is that of THHN cable with continuous maximum permissible temperature of $90^{\circ} \mathrm{C}$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}$ or less and wiring is performed in an enclosure.
${ }^{* 3}$ For the 00930 or less, the recommended cable size is that of the PVC cable with continuous maximum permissible temperature of $70^{\circ} \mathrm{C}$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}$ or less and the wiring distance is 20 m or less.
For the 01160 or more, the recommended cable size is that of XLPE cable with continuous maximum permissible temperature of $90^{\circ} \mathrm{C}$. Assumes that the ambient temperature is $40^{\circ} \mathrm{C}$ or less and wiring is performed in an enclosure.
${ }^{* 4}$ The terminal screw size indicates the terminal size for R/L1, S/L2, T/L3, U, V, W, and a screw for earthing.
For the 04320 or more, screw sizes are different. (R/L1, S/L2, T/L3, U, V, W / a screw for earthing)
The line voltage drop can be calculated by the following expression:
line voltage drop $[\mathrm{V}]=\frac{\sqrt{3} \times \text { wire resistance }[\Omega] \times \text { wiring distance }[\mathrm{m}] \times \text { current }[\mathrm{A}]}{1000}$
Use a larger diameter cable when the wiring distance is long or when it is desired to decrease the voltage drop (torque reduction) in the low speed range.

## - CAUTION

- Tighten the terminal screw to the specified torque.

A screw that has been tighten too loosely can cause a short circuit or malfunction.
A screw that has been tighten too tightly can cause a short circuit or malfunction due to the unit breakage.

- Use crimping terminals with insulation sleeve to wire the power supply and motor.


### 3.2.2 Total wiring length

The maximum possible length of the motor cables depends on the capacity of the inverter and the selected carrier frequency. The cables should never be longer than 500 m (unshielded).
The lengths in the following table are for unshielded cables. When shielded cables are use divide the values listed in the table by 2. Note that the values are for the total wiring length - if you connect more than one motor in parallel you must add the lengths of the individual motor cables.

| Pr. 72 PWM frequency selection setting (carrier frequency) | $\mathbf{0 0 0 2 3}$ | $\mathbf{0 0 0 3 8}$ | $\mathbf{0 0 0 5 2}$ or more |
| :---: | :---: | :---: | :---: |
| $2(2 \mathrm{kHz})$ or less | 300 m | 500 m | 500 m |
| $3(3 \mathrm{kHz}), 4(4 \mathrm{kHz})$ | 200 m | 300 m | 500 m |
| $5(5 \mathrm{kHz})$ to $9(9 \mathrm{kHz})$ |  | 100 m |  |
| $10(10 \mathrm{kHz})$ or more | 50 m |  |  |

## Note

- For the 01800 or more, the setting range of Pr. 72 PWM frequency selection is " 0 to 6 ".

Note that the motor windings in three-phase AC motors are subject to far more stress when operated via frequency inverters than with mains operation. The motor must have been approved by the manufacturer for operation on a frequency inverter.

## CAUTION

- Especially for long-distance wiring (particularly when employing shielded motor cables), the inverter may be affected by a charging current caused by the stray capacitances of the wiring, leading to a malfunction of the overcurrent protective function or fast response current limit function or a malfunction or fault of the equipment connected on the inverter output side.
When the fast-response current limit function malfunctions, make the function invalid. (For Pr. 156 Stall prevention operation selection, refer to the Instruction Manual (applied).)
- For details of Pr. 72 PWM frequency selection, refer to the Instruction Manual (applied).


### 3.2.3 Cable size of the control circuit power supply (terminal R1/L11, S1/L21)

- Terminal Screw Size: M4
- Cable size: $0.75 \mathrm{~mm}^{2}$ to $2 \mathrm{~mm}^{2}$
- Tightening torque: $1.5 \mathrm{~N} \cdot \mathrm{~m}$


### 3.3 Control circuit terminals

### 3.3.1 Terminal layout



### 3.3.2 Instructions for wiring of the control circuit terminal

- Terminals PC, 5, and SE are all common terminals ( $O V$ ) for I/O signals and are isolated from each other. Avoid connecting the terminal PC and 5 and the terminal SE and 5 . Terminal PC is a common terminal for the contact input terminals (STF, STR, STOP, RH, RM, RL, JOG, RT, MRS, RES,AU, CS).
- Use shielded or twisted cables for connection to the control circuit terminals and run them away from the main and power circuits (including the 230 V relay sequence circuit).
- Use two or more parallel micro-signal contacts or twin contacts to prevent a contact faults when using contact inputs since the control circuit input signals are microcurrents.



Twin contacts

- Do not apply a voltage to the contact input terminals (e.g. STF) of the control circuit.
- Always apply a voltage to the alarm output terminals (A, B, C) via a relay coil, lamp, etc.
- It is recommended to use the cables of $0.75 \mathrm{~mm}^{2}$ gauge for connection to the control circuit terminals. If the cable gauge used is $1.25 \mathrm{~mm}^{2}$ or more, the front cover may be lifted when there are many cables running or the cables are run improperly, resulting in an operation panel contact fault.
- The wiring length should be 30 m maximum.
- The level of the control signals can be switched over between positive (SOURCE) and negative (SINK) logic. The input signals are set to source logic when shipped from the factory. To change the control logic, the jumper connector on the control circuit terminal block must bemoved to the other position.


## 4 PRECAUTIONS FOR USE OF THE INVERTER

The FR-F700 series is a highly reliable product, but incorrect peripheral circuit making or operation/handling method may shorten the product life or damage the product.
Before starting operation, always recheck the following items.

- Use crimping terminals with insulation sleeve to wire the power supply and motor.
- Application of power to the output terminals ( $\mathrm{U}, \mathrm{V}, \mathrm{W}$ ) of the inverter will damage the inverter. Never perform such wiring.
- After wiring, wire offcuts must not be left in the inverter.

Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean. When drilling mounting holes in a control box etc., take care not to allow chips and other foreign matter to enter the inverter.

- Use cables of the size to make a voltage drop $2 \%$ maximum.

If the wiring distance is long between the inverter and motor, a main circuit cable voltage drop will cause the motor torque to decrease especially at the output of a low frequency.
Refer to page 7 for the recommended cable size.

- The overall wiring length should be 500 m maximum. Especially for long distance wiring, the fast-response current limit function may be reduced or the equipment connected to the inverter output side may malfunction or become faulty under the influence of a charging current due to the stray capacity of the wiring. Therefore, note the overall wiring length. (Refer to page 7)
- Electromagnetic Compatibility

Operation of the frequency inverter can cause electromagnetic interference in the input and output that can be propagated by cable (via the power input lines), by wireless radiation to nearby equipment (e.g. AM radios) or via data and signal lines. Activate the integrated EMC filter (and an additional optional filter if present) to reduce air propagated interference on the input side of the inverter. Use AC or DC reactors to reduce line propagated noise (harmonics). Use shielded motor power lines to reduce output noise.

- Do not install a power factor correction capacitor, varistor or arrester on the inverter output side. This will cause the inverter to trip or the capacitor, varistor, or arrester to be damaged. If any of the above devices is installed, immediately remove it.
- Before starting wiring or other work after the inverter is operated, wait for at least 10 minutes after the power supply has been switched off, and check that there are no residual voltage using a tester or the like. The capacitor is charged with high voltage for some time after power off and it is dangerous.
- A short circuit or earth fault on the inverter output side may damage the inverter modules.
- Fully check the insulation resistance of the circuit prior to inverter operation since repeated short circuits caused by peripheral circuit inadequacy or an earth fault caused by wiring inadequacy or reduced motor insulation resistance may damage the inverter modules.
- Fully check the to-earth insulation and inter-phase insulation of the inverter output side before power-on.

Especially for an old motor or use in hostile atmosphere, securely check the motor insulation resistance etc.

- Do not use the inverter input side magnetic contactor to start/stop the inverter.

Always use the start signal (ON/OFF of STF and STR signals) to start/stop the inverter.

- Do not apply a voltage higher than the permissible voltage to the inverter I/O signal circuits.

Contact to the inverter I/O signal circuits or opposite polarity may damage the I/O devices. Especially check the wiring to prevent the speed setting potentiometer from being connected incorrectly to short terminals 10E (10, respectively) -5 .

- Provide electrical and mechanical interlocks for MC1 and MC2 which are used for commercial power supply-inverter switch-over.
When the wiring is incorrect or if there is a commercial power supply-inverter switch-over circuit as shown below, the inverter will be damaged by leakage current from the power supply due to arcs generated at the time of switch-over or chattering caused by a sequence error.

- If the machine must not be restarted when power is restored after a power failure, provide a magnetic contactor in the inverter's input side and also make up a sequence which will not switch on the start signal.
If the start signal (start switch) remains on after a power failure, the inverter will automatically restart as soon as the power is restored.
- Instructions for overload operation

When performing operation of frequent start/stop of the inverter, increase/decrease in the temperature of the transistor element of the inverter may repeat due to a continuous flow of large current, shortening the life from thermal fatigue. Since thermal fatigue is related to the amount of current, the life can be increased by reducing bound current, starting current, etc. Decreasing current may increase the life. However, decreasing current will result in insufficient torque and the inverter may not start. Therefore, increase the inverter capacity to have enough allowance for current.

- Make sure that the specifications and rating match the system requirements.


## 5 PARAMETER

### 5.1 Parameter list

In the initial setting, only the simple mode parameters are displayed.
Set Pr. 160 User group read selection as required.

| Parameter | Name | Initial <br> Value | Setting <br> Range | Remarks |
| :---: | :---: | :---: | :---: | :--- |
| $\mathbf{1 6 0}$ | User group read selection | 9999 | 9999 | Only the simple mode parameters can be displayed. |
|  |  |  | Simple mode and extended mode parameters can be <br> displayed. |  |
|  |  | 1 | Only parameters registered in the user group can be displayed. |  |

## Remarks

- The parameters marked © are the simple mode parameters.
- The parameters marked with $\square$ in the table allow its setting to be changed during operation even if " 0 " (initial value) is set in Pr. 77 Parameter write selection.
- Parameters for the option are displayed only when the option unit is installed.

| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| (-) 0 | Torque boost | 0 to 30\% | $\begin{gathered} 6 / 4 / 3 / 2 / 1.5 / \\ 1 \% * 2 \end{gathered}$ |
| (0) 1 | Maximum frequency | 0 to 120 Hz | $120 / 60 \mathrm{~Hz}$ *1 |
| (-) 2 | Minimum frequency | 0 to 120 Hz | 0 Hz |
| (0) 3 | Base frequency | 0 to 400 Hz | 50 Hz |
| (0) 4 | Multi-speed setting (high speed) | 0 to 400Hz | 50 Hz |
| (0) 5 | Multi-speed setting (middle speed) | 0 to 400Hz | 30 Hz |
| (0) 6 | Multi-speed setting (low speed) | 0 to 400 Hz | 10Hz |
| (0) 7 | Acceleration time | 0 to 3600/360s | $5 \mathrm{~s} / 15 \mathrm{~s}$ *3 |
| (0) 8 | Deceleration time | 0 to 3600/360s | 10s/30s *3 |
| (0) 9 | Electronic thermal O/L relay | $\begin{aligned} & 0 \text { to 500/ } \\ & 0 \text { to } 3600 \mathrm{~A} \text { *1 } \end{aligned}$ | Rated inverter output current |
| 10 | DC injection brake operation frequency | $\begin{aligned} & 0 \text { to } 120 \mathrm{~Hz} \text {, } \\ & 9999 \end{aligned}$ | 3 Hz |
| 11 | DC injection brake operation time | 0 to 10s, 8888 | 0.5s |
| 12 | DC injection brake operation voltage | 0 to 30\% | 4/2/1\% *4 |
| 13 | Starting frequency | 0 to 60 Hz | 0.5 Hz |
| 14 | Load pattern selection | 0, 1 | 1 |
| 15 | Jog frequency | 0 to 400 Hz | 5 Hz |
| 16 | Jog acceleration/ deceleration time | 0 to 3600/360s | 0.5s |


| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| 17 | MRS input selection | 0, 2 | 0 |
| 18 | High speed maximum frequency | 120 to 400 Hz | $120 / 60 \mathrm{~Hz}$ *1 |
| 19 | Base frequency voltage | 0 to 1000 V , <br> 8888, 9999 | 8888 |
| 20 | Acceleration/ deceleration reference frequency | 1 to 400 Hz | 50 Hz |
| 21 | Acceleration/ deceleration time increments | 0,1 | 0 |
| 22 | Stall prevention operation level | 0 to 120\%, 9999 | 110\% |
| 23 | Stall prevention operation level compensation factor at double speed | 0 to 150\%, 9999 | 9999 |
| 24 to 27 | Multi-speed setting 4 speed to 7 speed | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 28 | Multi-speed input compensation selection | 0,1 | 0 |
| 29 | Acceleration/ deceleration pattern selection | 0, 1, 2, 3 | 0 |
| 30 | Regenerative function selection | 0, 2/0, 1, 2 *1 | 0 |
| 31 | Frequency jump 1A | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 32 | Frequency jump 1B | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |

[^0]| Parameters | Name | Setting Range | Initial Value | Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 33 | Frequency jump 2A | $\begin{array}{\|l\|} \hline 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \end{array}$ | 9999 | 67 | Number of retries at alarm occurrence | $\begin{aligned} & 0,1 \text { to } 10, \\ & 101 \text { to } 110 \end{aligned}$ | 0 |
| 34 | Frequency jump 2B | $\begin{aligned} & \hline \begin{array}{l} 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \end{array} \\ & \hline \end{aligned}$ | 9999 | 68 | Retry waiting time | 0 to 10s | 1s |
| 35 | Frequency jump 3A | $\begin{array}{\|l\|} \hline 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \end{array}$ | 9999 | 69 | Retry count display erase | 0 | 0 |
| 36 | Frequency jump 3B | $\begin{aligned} & \begin{array}{l} 0 \text { to } \\ 9999 \end{array} \end{aligned}$ | 9999 | 70 | Special regenerative brake duty *3 | 0 to 10\% | 0\% |
| 37 | Speed display | 0, 1 to 9998 | 0 | 71 | Applied motor | 0, 1, 2, 20 | 0 |
| 41 | Up-to-frequency sensitivity | 0 to 100\% | 10\% | 72 | PWM frequency selection | $\begin{array}{\|l\|} \hline 0 \text { to } 15 / \\ 0 \text { to } 6,25 * 1 \end{array}$ | 2 |
| 42 | Output frequency detection | 0 to 400 Hz | 6 Hz | 73 | Analog input selection | 0 to 7, 10 to 17 | 1 |
| 43 | Output frequency detection for reverse | $\begin{array}{\|l} 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \end{array}$ | 9999 | 74 | Input filter time constant | 0 to 8 | 1 |
| 44 | rotation <br> Second acceleration/ deceleration time | 0 to 3600/360s | 5 s | 75 | Reset selection/ disconnected PU detection/PU stop | 0 to 3, 14 to 17, <br> 100 to 103, <br> 114 to 117 * | 14 |
| 45 | Second deceleration time | $\begin{aligned} & 0 \text { to } \begin{array}{l} \text { 3600/360s, } \\ 9999 \end{array} \end{aligned}$ | 9999 |  | selection <br> Alarm code output | 0, 1, 2 | 0 |
| 46 | Second torque boost | 0 to 30\%, 9999 | 9999 |  |  |  |  |
| 47 | Second V/F (base frequency) | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 | 77 | Parameter write selection | 0, 1, 2 | 0 |
| 48 | Second stall prevention operation | 0.1 to 120\% | 110\% | 78 | Reverse rotation prevention selection | 0, 1, 2 | 0 |
|  | current |  |  | © 79 | Operation mode selection | 0, 1, 2, 3, 4, 6, 7 | 0 |
| 49 | Second stall prevention operation frequency | $\left\lvert\, \begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}\right.$ | OHz | 80 | selection <br> Motor capacity (simple magnetic | $0.4 \text { to } 55 \mathrm{~kW} \text {, }$ $9999 /$ | 9999 |
| 50 | Second output frequency detection | 0 to 400 Hz | 30 Hz |  | flux vector control) | $9999 * 1$ |  |
| 51 | Second electronic | $0 \text { to 500A, }$ $9999 /$ | 9999 | 90 | Motor constant (R1) | $\begin{aligned} & 0 \text { to } 50 \Omega, 9999 / \\ & 0 \text { to } 400 \mathrm{~m} \Omega, \\ & 9999 * 1 \end{aligned}$ | 9999 |
|  |  | $9999 * 1$ |  | 100 | V/F1 (first frequency) | $\begin{aligned} & \hline \begin{array}{l} 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \end{array} \\ & \hline \end{aligned}$ | 9999 |
| 52 | DU/PU main display data selection | $0,5,6,8$ to 14 , 17, 20, 23 to 25 , 50 to 57,100 *2 | 0 | 101 | V/F1 (first frequency voltage) | 0 to 1000 V | OV |
| 54 | CA terminal function | $\begin{aligned} & 1 \text { to } 3,5,6, \\ & 8 \text { to } 14,17,21, \end{aligned}$ | 1 | 102 | V/F2 (second frequency) | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
|  |  | 24, 50, 52, 53 |  | 103 | V/F2 (second | 0 to 1000V | OV |
| 55 | Frequency monitoring reference | 0 to 400 Hz | 50 Hz |  | frequency voltage) | 0 to 400 Hz , |  |
|  |  |  | Rated |  | frequency) | 9999 | 99 |
| 56 | Current monitoring reference | $\left\lvert\, \begin{aligned} & 0 \text { to } 500 \mathrm{~A} / \\ & 0 \text { to } 3600 \mathrm{~A} \end{aligned}\right.$ | inverter output current | 105 | V/F3 (third frequency voltage) | 0 to 1000V | OV |
|  |  | $\begin{aligned} & \text { 0, 0.1 to } 5 \mathrm{~s}, \\ & 9999 / \end{aligned}$ |  | 106 | V/F4 <br> (fourth frequency) | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 57 | R | $\begin{aligned} & 0,0.1 \text { to } 30 \mathrm{~s}, \\ & 9999 * 1 \\ & \hline \end{aligned}$ | 99 | 107 | V/F4 (fourth frequency voltage) | 0 to 1000V | OV |
| 58 | Restart cushion time | 0 to 60s | 1s | 108 | V/F5 (fifth frequency) | $\begin{aligned} & \hline \begin{array}{l} 0 \text { to } 400 \mathrm{~Hz}, \\ 9999 \end{array} \end{aligned}$ | 9999 |
| 59 | Remote function selection | 0, 1, 2, 3 | 0 | 109 | V/F5 (fifth frequency voltage) | 0 to 1000 V | OV |
| © 60 | Energy saving control selection | 0, 4, 9 | 0 | 117 | PU communication | 0 to 31 | 0 |
| 65 | Retry selection | 0 to 5 | 0 |  |  |  |  |
| 66 | Stall prevention operation reduction starting frequency | 0 to 400 Hz | 50 Hz | 118 | PU communication speed | 48, 96, 192, 384 | 192 |

[^1]| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| 119 | PU communication stop bit length. | 0, 1, 10, 11 | 1 |
| 120 | PU communication parity check | 0, 1, 2 | 2 |
| 121 | Number of PU communication retries | 0 to 10, 9999 | 1 |
| 122 | PU communication check time interval | $\begin{aligned} & 0,0.1 \text { to } 999.8 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 9999 |
| 123 | PU communication waiting time setting | 0 to 150 ms , 9999 | 9999 |
| 124 | PU communication CR/LF presence/ absence selection | 0,1, 2 | 1 |
| (0) 125 | Terminal 2 frequency setting gain frequency | 0 to 400 Hz | 50 Hz |
| (0) 126 | Terminal 4 frequency setting gain frequency | 0 to 400 Hz | 50 Hz |
| 127 | PID control automatic switchover freqeuncy | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz} \text {, } \\ & 9999 \end{aligned}$ | 9999 |
| 128 | PID action selection | $\begin{aligned} & 10,11,20,21, \\ & 50,51,60,61 \end{aligned}$ | 10 |
| 129 | PID proportional band | $\begin{aligned} & 0.1 \text { to } 1000 \% \text {, } \\ & 9999 \end{aligned}$ | 100\% |
| 130 | PID integral time | $\begin{aligned} & 0.1 \text { to } 3600 \mathrm{~s} \text {, } \\ & 9999 \end{aligned}$ | 1s |
| 131 | PID upper limit | $\begin{aligned} & 0 \text { to } 100 \% \text {, } \\ & 9999 \end{aligned}$ | 9999 |
| 132 | PID lower limit | $\begin{aligned} & 0 \text { to } 100 \% \text {, } \\ & 9999 \end{aligned}$ | 9999 |
| 133 | PID action set point | $\begin{aligned} & 0 \text { to 100\%, } \\ & 9999 \end{aligned}$ | 9999 |
| 134 | PID differential time | $\begin{aligned} & 0.01 \text { to } 10.00 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 9999 |
| 135 | Commercial powersupply switchover sequence output terminal selection | 0,1 | 0 |
| 136 | MC switchover interlock time | 0 to 100s | 1s |
| 137 | Start waiting time | 0 to 100s | 0.5s |
| 138 | Commercial powersupply operation switchover selection at an alarm | 0,1 | 0 |
| 139 | Automatic switchover frequency between inverter and commercial powersupply operation | $\begin{aligned} & 0 \text { to } 60 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 140 | Backlash acceleration stopping frequency | 0 to 400 Hz | 1 Hz |
| 141 | Backlash acceleration stopping time | 0 to 360s | 0.5s |


| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| 142 | Backlash deceleration stopping frequency | 0 to 400 Hz | 1 Hz |
| 143 | Backlash deceleration stopping time | 0 to 360s | 0.5 s |
| 144 | Speed setting switchover | $\begin{aligned} & 0,2,4,6,8,10, \\ & 102,104,106, \\ & 108,110 \end{aligned}$ | 4 |
| 145 | PU display language selection | 0 to 7 | 1 |
| 148 | Stall prevention level at OV input. | 0 to 120\% | 110\% |
| 149 | Stall prevention level at 10 V input. | 0 to 120\% | 120\% |
| 150 | Output current detection level | 0 to 120\% | 110\% |
| 151 | Output current detection signal delay time | 0 to 10s | Os |
| 152 | Zero current detection level | 0 to 150\% | 5\% |
| 153 | Zero current detection time | 0 to 1s | 0.5 s |
| 154 | Voltage reduction selection during stall prevention operation | 0, 1 | 1 |
| 155 | RT signal reflection time selection | 0, 10 | 0 |
| 156 | Stall prevention operation selection | $\begin{aligned} & 0 \text { to } 31,100, \\ & 101 \end{aligned}$ | 0 |
| 157 | OL signal output timer | 0 to 25s, 9999 | Os |
| 158 | AM terminal function selection | $\begin{aligned} & 1 \text { to } 3,5,6, \\ & 8 \text { to } 14,17,21, \\ & 24,50,52,53 \end{aligned}$ | 1 |
| 159 | Automatic switchover ON range between commercial power-supply and inverter operation | 0 to $10 \mathrm{~Hz}, 9999$ | 9999 |
| ©160 | User group read selection | 0,1,9999 | 9999 |
| 161 | Frequency setting/ key lock operation selection | 0, 1, 10, 11 | 0 |
| 162 | Automatic restart after instantaneous power failure selection | 0, 1, 10, 11 | 0 |
| 163 | First cushion time for restart | 0 to 20s | Os |
| 164 | First cushion voltage for restart | 0 to 100\% | 0\% |
| 165 | Stall prevention operation level for restart | 0 to 120\% | 110\% |
| 166 | Output current detection signal retention time | 0 to 10s, 9999 | 0.1 s |
| 167 | Output current detection operation selection | 0,1 | 0 |

[^2]| Parameters | Name | Setting Range | Initial Value | Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 168 | Parameter for manufacturer setting. Do not make setting. |  |  | 195 | ABC1 terminal function selection | 0 to 5, 7, 8, 10 to <br> 19, 25, 26, 45 to <br> 47, 64, 70 to 78 , <br> 90, 91, 94 to 96, <br> 98, 99, 100 to <br> 105, 107, 108, <br> 110 to 116, 125, <br> 126, 145 to 147, <br> 164, 170, 190, <br> 191, 194 to <br> 196,198, 199, <br> 9999 * | 99 |
| 169 |  |  |  |  |  |  |  |
| 170 | Cumulative power meter clear | 0, 10, 9999 | 9999 |  |  |  |  |
| 171 | Operation hour meter clear | 0,9999 | 9999 |  |  |  |  |
| 172 | User group registered display/ batch clear | 9999, (0 to 16) | 0 | 196 | ABC2 terminal function selection |  | 9999 |
| 173 | User group registration | 0 to 999, 9999 | 9999 | $\begin{gathered} 232 \\ \text { to } \\ 239 \end{gathered}$ | Multi-speed setting (speeds 8 to 15) | $\begin{aligned} & 0 \text { to } 400 \mathrm{~Hz}, \\ & 9999 \end{aligned}$ | 9999 |
| 174 | User group clear | 0 to 999, 9999 | 9999 |  |  |  |  |
| 178 | STF terminal function selection | $\begin{aligned} & 0 \text { to } 8,10 \text { to } 14, \\ & 16,24,25,37, \\ & 60,62,64 \text { to } 67, \\ & 9999 \end{aligned}$ | 60 | 240 | Soft-PWM operation selection | 0, 1 | 1 |
|  |  |  |  | 241 | Analog input display unit switchover | 0, 1 | 0 |
|  |  | $0 \text { to } 8,10 \text { to } 14 \text {, }$ |  |  |  |  |  |
| 179 | function selection | 61, 62, 64 to 67 , 9999 | 61 | 242 | Terminal 1 added compensation amount (terminal 2) | 0 to 100\% | 100\% |
| 180 | RL terminal function selection | $\begin{aligned} & 0 \text { to } 8,10 \text { to } 14 \text {, } \\ & 16,24,25,37, \\ & 62,64 \text { to } 67 \text {, } \\ & 9999 \end{aligned}$ | 0 | 243 | Terminal 1 added compensation amount (terminal 4) | 0 to 100\% | 75\% |
| 181 | RM terminal function selection |  | 1 |  |  |  |  |
| 182 | RH terminal function selection |  | 2 | 244 | Cooling fan operation selection | 0,1 | 1 |
|  | RT terminal function |  |  | 245 | Rated slip | 0 to 50\%, 9999 | 9999 |
| 183 | selection |  | 3 | 246 | Slip compensation time constant | 0.01 to 10s | 0.5s |
| 184 | AU terminal function selection | $\begin{aligned} & 0 \text { to } 8,10 \text { to } 14, \\ & 16,24,25,37, \\ & 62 \text { to } 67,9999 \end{aligned}$ | 4 | 247 | Constant-output region slip compensation selection | 0,9999 | 9999 |
| 185 | JOG terminal function selection | $\begin{aligned} & 0 \text { to } 8,10 \text { to } 14 \text {, } \\ & 16,24,25,37, \\ & 62,64 \text { to } 67, \\ & 9999 \end{aligned}$ | 5 |  |  |  |  |
| 186 | CS terminal function selection |  | 6 | 250 | Stop selection | 0 to 100s, 1000 to 1100 s , 8888, 9999 | 9999 |
| 187 | MRS terminal function selection |  | 24 | 251 | Output phase failure protection selection | 0,1 | 1 |
| 188 | STOP terminal function selection |  | 25 | 252 | Override bias | 0 to 200\% | 50\% |
| 189 | RES terminal |  | 62 | 253 | Override gain | 0 to 200\% | 150\% |
|  | function selection |  |  | 255 | Life alarm status | (0 to 15) | 0 |
| 190 | RUN terminal | 0 to 5, 7, 8, <br> 10 to 19, 25, 26, 45 to 47, 64, <br> 70 to 78,90 to 96, 98, 99, <br> 100 to 105, 107, <br> 108, 110 to 116, <br> 125, 126, <br> 145 to 147, 164, <br> 170, 190 to 196, <br> 198, 199, 9999 | 0 |  | display |  |  |
|  | function selection |  |  | 256 | Inrush current suppression circuit life display | (0 to 100\%) | 100\% |
| 191 | SU terminal function |  | 1 |  |  |  |  |
|  | sel |  |  | 257 | Control circuit capacitor life display | (0 to 100\%) | 100\% |
| 192 | IPF terminal function selection |  | 2 | 258 | Main circuit capacitor life display | (0 to 100\%) | 100\% |
| 193 | OL terminal function selection |  | 3 | 259 | Main circuit capacitor life measuring | 0,1 | 0 |
| 194 | FU terminal function selection |  | 4 |  |  |  |  |

[^3]| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| 260 | PWM frequency automatic switchover | 0,1 | 1 |
| 261 | Power failure stop selection | 0, 1, 2 | 0 |
| 262 | Subtracted frequency at deceleration start | 0 to 20 Hz | 3 Hz |
| 263 | Subtraction starting frequency | $\begin{aligned} & 0 \text { to } 120 \mathrm{~Hz} \text {, } \\ & 9999 \end{aligned}$ | 50 Hz |
| 264 | Power-failure deceleration time 1 | 0 to 3600/360s | 5s |
| 265 | Power-failure deceleration time 2 | $\begin{aligned} & 0 \text { to } 3600 / 360 s \text {, } \\ & 9999 \end{aligned}$ | 9999 |
| 266 | Power failure deceleration time switchover frequency | 0 to 400 Hz | 50 Hz |
| 267 | Terminal 4 input selection | 0, 1, 2 | 0 |
| 268 | Monitor decimal digits selection | 0, 1, 9999 | 9999 |
| 269 | Parameter for manufacturer setting. Do not make setting. |  |  |
| 299 | Rotation direction detection selection at restarting | 0, 1, 9999 | 9999 |
| 331 | RS-485 communication station | $\begin{aligned} & 0 \text { to } 31 \\ & (0 \text { to } 247) \end{aligned}$ | 0 |
| 332 | RS-485 communication speed | $\begin{aligned} & 3,6,12,24, \\ & 48,96,192,384 \end{aligned}$ | 96 |
| 333 | RS-485 <br> communication stop bit length | 0, 1, 10, 11 | 1 |
| 334 | RS-485 <br> communication parity check selection | 0, 1, 2 | 2 |
| 335 | RS-485 communication number of retries | 0 to 10, 9999 | 1 |
| 336 | RS-485 communication check time interval | $\begin{aligned} & 0 \text { to } 999.8 \mathrm{~s}, \\ & 9999 \end{aligned}$ | Os |
| 337 | RS-485 communication waiting time setting | 0 to 150 ms , 9999 | 9999 |
| 338 | Communication operation command source | 0,1 | 0 |
| 339 | Communication speed command source | 0, 1, 2 | 0 |
| 340 | Communication startup mode selection | 0, 1, 2, 10, 12 | 0 |
| 341 | RS-485 <br> communication CR/LF selection | 0, 1, 2 | 1 |
| 342 | Communication EEPROM write selection | 0,1 | 0 |


| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| 343 | Communication error count | - | 0 |
| 495 | Remote output selection | 0, 1 | 0 |
| 496 | Remote output data 1 | 0 to 4095 | 0 |
| 497 | Remote output data 2 | 0 to 4095 | 0 |
| 503 | Maintenance timer | 0 (1 to 9998) | 0 |
| 504 | Maintenance timer alarm output set time | 0 to 9998, 9999 | 9999 |
| 549 | Protocol selection | 0,1 | 0 |
| 550 | NET mode operation command source selection | 0, 1, 9999 | 9999 |
| 551 | PU mode operation command source selection | 1,2 | 2 |
| 555 | Current average time | 0.1 to 1.0s | 1 s |
| 556 | Data output mask time | 0.0 to 20.0s | Os |
| 557 | Current average value monitor signal output reference current | $\begin{aligned} & 0 \text { to 500A/ } \\ & 0 \text { to } 3600 \mathrm{~A} \text { *1 } \end{aligned}$ | Rated inverter current |
| 563 | Energization time carrying-over times | (0 to 65535) | 0 |
| 564 | Operating time carrying-over times | (0 to 65535) | 0 |
| 570 | Multiple rating setting | 0, 1 | 0 |
| 571 | Holding time at a start | $\begin{aligned} & 0.0 \text { to } 10.0 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 9999 |
| 573 | 4mA Input check selection | 1,9999 | 9999 |
| 575 | Output interruption detection time | $\begin{aligned} & 0 \text { to } 3600 \text { s, } \\ & 9999 \end{aligned}$ | 1s |
| 576 | Output interruption detection level | 0 to 400Hz | OHz |
| 577 | Output interruption release level | 900 to 1100\% | 1000\% |
| 578 | Auxiliary motor operation selection | 0 to 3 | 0 |
| 579 | Motor swichover selection | 0 to 3 | 0 |
| 580 | MC switching interlock time | 0 to 100s | 1s |
| 581 | Start waiting time | 0 to 100s | 1s |
| 582 | Auxiliary motor connection-time deceleration time | $\begin{aligned} & 0 \text { to } 3600 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 1s |
| 583 | Auxiliary motor disconnection-time acceleration time | $\begin{aligned} & 0 \text { to } 3600 \mathrm{~s}, \\ & 9999 \end{aligned}$ | 1s |
| 584 | Auxiliary motor 1 starting frequency | 0 to 400Hz | 50 Hz |
| 585 | Auxiliary motor 2 starting frequency | 0 to 400Hz | 50 Hz |
| 586 | Auxiliary motor 3 starting frequency | 0 to 400Hz | 50 Hz |
| 587 | Auxiliary motor 1 stopping frequency | 0 to 400Hz | OHz |

[^4]| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| 588 | Auxiliary motor 2 stopping frequency | 0 to 400 Hz | OHz |
| 589 | Auxiliary motor 3 stopping frequency | 0 to 400 Hz | OHz |
| 590 | Auxiliary motor start detection time | 0 to 3600s | 5s |
| 591 | Auxiliary motor stop detection time | 0 to 3600s | 5s |
| 592 | Traverse function selection | 0, 1, 2 | 0 |
| 593 | Maximum amplitude amount | 0 to 25\% | 10\% |
| 594 | Amplitude compensation amount during deceleration | 0 to 50\% | 10\% |
| 595 | Amplitude compensation amount during acceleration | 0 to 50\% | 10\% |
| 596 | Amplitude acceleration time | 0.1 to 3600s | 5s |
| 597 | Amplitude deceleration time | 0.1 to 3600s | 5s |
| 611 | Acceleration time at a restart | $\begin{aligned} & 0 \text { to 3600s, } \\ & 9999 \end{aligned}$ | 5/15s *1 |
| 867 | AM output filter | 0 to 5s | 0.01 s |
| 869 | Current output filter | 0 to 5s | 0.02 s |
| 872 | Input phase failure protection selection | 0, 1 | 0 |
| 882 | Regeneration avoidance operation selection | 0, 1 | 0 |
| 883 | Regeneration avoidance operation level | 300 to 800 V | 760VDC |
| 884 | Regeneration avoidance at deceleration detection sensitivity | 0 to 5 | 0 |
| 885 | Regeneration avoidance compensation frequency limit value | $\left\lvert\, \begin{aligned} & 0 \text { to } \\ & 9999 \end{aligned} 10 \mathrm{~Hz}\right.,$ | 6 Hz |
| 886 | Regeneration avoidance voltage gain | 0 to 200\% | 100\% |
| 888 | Free parameter 1 | 0 to 9999 | 9999 |
| 889 | Free parameter 2 | 0 to 9999 | 9999 |
| 891 | Cumulative power monitor digit shifted times | 0 to 4, 9999 | 9999 |
| 892 | Load factor | 30 to 150\% | 100\% |
| 893 | Energy saving monitor reference (motor capacity) | $\begin{array}{\|l} 0.1 \text { to } 55 \mathrm{~kW} / \\ 0 \text { to } 3600 \mathrm{~kW} \text { *1 } \end{array}$ | LD/SLD value of applied motor capacity |


| Parameters | Name | Setting Range | Initial Value |
| :---: | :---: | :---: | :---: |
| 894 | Control selection during commercial power-supply operation | 0, 1, 2, 3 | 0 |
| 895 | Power saving rate reference value | 0, 1, 9999 | 9999 |
| 896 | Power unit cost | 0 to 500, 9999 | 9999 |
| 897 | Power saving monitor average time | $\begin{aligned} & 0,1 \text { to } 1000 \mathrm{~h}, \\ & 9999 \end{aligned}$ | 9999 |
| 898 | Power saving cumulative monitor clear | 0, 1, 10, 9999 | 9999 |
| 899 | Operation time rate (estimated value) | $\begin{aligned} & 0 \text { to } 100 \%, \\ & 9999 \end{aligned}$ | 9999 |
| $\begin{gathered} \text { C0 } \\ (900) \end{gathered}$ | CA terminal calibration | - | - |
| $\begin{gathered} \text { C1 } \\ (901) \end{gathered}$ | AM terminal calibration | - | - |
| $\begin{gathered} \text { C2 } \\ (902) \end{gathered}$ | Terminal 2 frequency setting bias frequency | 0 to 400 Hz | OHz |
| $\begin{gathered} \text { C3 } \\ \text { (902) } \end{gathered}$ | Terminal 2 frequency setting bias | 0 to 300\% | 0\% |
| $\begin{gathered} 125 \\ (903) \end{gathered}$ | Terminal 2 frequency setting gain frequency | 0 to 400 Hz | 50 Hz |
| $\begin{gathered} \hline \text { C4 } \\ \text { (903) } \end{gathered}$ | Terminal 2 frequency setting gain | 0 to 300\% | 100\% |
| $\begin{gathered} \text { C5 } \\ (904) \end{gathered}$ | Terminal 4 frequency setting bias frequency | 0 to 400 Hz | 0Hz |
| $\begin{gathered} \text { C6 } \\ (904) \end{gathered}$ | Terminal 4 frequency setting bias | 0 to 300\% | 20\% |
| $\begin{gathered} 126 \\ (905) \end{gathered}$ | Terminal 4 frequency setting gain frequency | 0 to 400 Hz | 50 Hz |
| $\begin{gathered} \text { C7 } \\ \text { (905) } \end{gathered}$ | Terminal 4 frequency setting gain | 0 to 300\% | 100\% |
| $\begin{gathered} \text { C8 } \\ (930) \end{gathered}$ | Current output bias signal | 0 to 100\% | 0\% |
| $\begin{gathered} \text { C9 } \\ \text { (930) } \end{gathered}$ | Current output bias current | 0 to 100\% | 0\% |
| $\begin{gathered} \text { C10 } \\ \text { (931) } \end{gathered}$ | Current output gain signal | 0 to 100\% | 100\% |
| $\begin{gathered} \text { C11 } \\ (931) \end{gathered}$ | Current output gain current | 0 to 100\% | 100\% |
| 989 | Parameter copy alarm release | 10/100 *1 | 10/100 *1 |
| 990 | PU buzzer control | 0, 1 | 1 |
| © 991 | PU contrast adjustment | 0 to 63 | 58 |
| Pr.CL | Parameter clear | 0, 1 | 0 |
| ALLC | All parameter clear | 0, 1 | 0 |
| Er.CL | Alarm history clear | 0, 1 | 0 |
| PCPY | Parameter copy | 0, 1, 2, 3 | 0 |

[^5]
## 6 TROUBLESHOOTING

When an alarm occurs in the inverter, the protective function is activated bringing the inverter to an alarm stop and the PU display automatically changes to any of the following error (alarm) indications.
If your fault does not correspond to any of the following errors or if you have any other problem, please contact your sales representative.

- Retention of alarm output signal...... When the magnetic contactor (MC) provided on the input side of the inverter is opened at the activation of the protective function, the inverter's control power will be lost and the alarm output will not be held.
- Alarm display When the protective function is activated, the operation panel display automatically switches to the
- Resetting method above indication. When a protective function of the inverter is activated, the power output of the inverter is blocked (motor is coasting). The inverter cannot start up again unless an automatic restart has been configured or the inverter is reset. Please observe carefully the warnings contained below in the configuration of an automatic restart or the execution of a reset.
- If protective functions were activated (i. e. the inverter switched off with an error message) follow the instructions for error correction provided in the manual for the inverter. Especially in the case of short circuits or earth contacts in the inverter output and mains overvoltages the cause of the fault must be determined prior to switching on again as a recurrence of such faults at short intervals can lead to premature aging of components or even the complete breakdown of the device. After the cause of the fault has been found and corrected the inverter can be reset and operations continue.


### 6.1 List of alarm display

| Operation Panel |  |  |
| :--- | :--- | :--- | :--- |
|  | Indication | Name |



If when employing the operating unit FR-PU04 one of the errors "E.ILF, E.PTC, E.PE2, E.CDO, E.IOH, E.SER, E.AIE, E.13" occurs, then "Fault 14" will be displayed.

## A. 1 Instructions for Compliance with the European Directives

## A.1.1 EMC Directive

We have self-confirmed our inverters as products compliant to the EMC Directive (second environment of conforming standard EN61800-3) and place the CE mark on the inverters.

## Remarks

- First environment

Environment including residential buildings. Includes buildings directly connected without a transformer to the low voltage power supply network which supplies power to residential buildings.

- Second environment Environment including all buildings except buildings directly connected without a transformer to the low voltage power supply network which supplies power to residential buildings.


## A.1.2 Notes

Install the inverter (and if necessary optional radio interference suppression filters) and perform wiring according to the following instructions.

- The inverter is equipped with a built-in EMC filter. Set the EMC filter valid (initial setting).
- Connect the inverter to an earthed power supply.
- Install a motor and a control cable written in the EMC Installation Manual (BCN-A21041-204) according to the instruction.
- The maximum cable length (shielded cable) between the frequency inverter and motor required to maintain the limiting values of the second environment is 5 m when using the internal radio interference suppression filter.
- Make sure that the frequency inverter, if required (optional external) radio interference suppression filters and the motor are installed in compliance with generally recognised EMC installation regulations. It is not permitted to start up the device unless the EMC guidelines are complied with.


## A.1.3 Low Voltage Directive

We have self-confirmed our inverters as products compliant to the Low Voltage Directive (Conforming standard EN 50178) and place the CE mark on the inverters.

## Outline of instructions

- Do not use a residual current operated protective device (RCD) as an electric shock protector without connecting the equipment to the earth. Connect the equipment to the earth securely.
- Wire the earth terminal independently. (Do not connect two or more cables to one terminal.)
- Use the cable sizes on page 7 under the following conditions.
- Ambient temperature: $40^{\circ} \mathrm{C}$ maximum
- Wire installation: With conduits for $400 \mathrm{~V}, 00380$ or less

On wall without ducts or conduits for $400 \mathrm{~V}, 00470$ or more
If conditions are different from above, select appropriate wire according to EN60204 Appendix C TABLE 5.

- Use a tinned (plating should not include zinc) crimping terminal to connect the earth cable. When tightening the screw, be careful not to damage the threads.
- For use as a product compliant with the Low Voltage Directive, use PVC cable whose size is indicated on page 7.
- Use the moulded case circuit breaker and magnetic contactor which conform to the EN or IEC Standard.
- Use the residual current operated protective device ( $R C D$ ) of type $B$ (breaker which can detect both $A C$ and DC). However, be aware that also AC/DC sensitive earth leakage circuit breakers can be activated when turning the main power on and off and that this behaviour can be improved through the use of AC/DC sensitive earth leakage circuit breakers with adapted triggering curve designed for the inverter. If not, provide double or reinforced insulation between the inverter and other equipment, or put a transformer between the main power supply and inverter.
- Use the inverter under the conditions of overvoltage category II (usable regardless of the earth condition of the power supply), overvoltage category III (usable with the earthed-neutral system power supply) and pollution degree 2 or lower specified in IEC664.
- To use the inverter FR-F 740 EC of 00770 or more (IP00) under the conditions of pollution degree 2, install it in the enclosure of IP 2X or higher.
- To use the inverter FR-F 740 EC under the conditions of pollution degree 3, install it in the enclosure of IP54 or higher.
- To use the inverter FR-F 740 EC of 00620 or less (IP20) outside of an enclosure in the environment of pollution degree 2 , fix a fan cover with fan cover fixing screws enclosed.

- On the input and output of the inverter, use cables of the type and size set forth in EN60204 Appendix C.
- The operating capacity of the relay outputs (terminal symbols A1, B1, C1, A2, B2, C2) should be 30VDC, 0.3A. (Relay outputs are basically isolated from the inverter internal circuit.)
- Control circuit terminals on page 4 are safely isolated from the main circuit.


## Environment

|  | During Operation |  | In Storage | During Transportation |
| :--- | :---: | :---: | :---: | :---: |
| Ambient temperature | $-10^{\circ} \mathrm{C}$ to $+40 /+50^{\circ} \mathrm{C}$ | $-10^{\circ} \mathrm{C}$ to $+30 /+40^{\circ} \mathrm{C}$ | $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ | $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ |
|  | The maximum temperature depends on the setting of the Pr. 570. |  |  |  |
| Ambient humidity | $90 \%$ RH or less | $90 \% \mathrm{RH}$ or less | $90 \% \mathrm{RH}$ or less | $90 \%$ |
| Maximum altitude | 1000 m | 1000 m | 1000 m | 10000 m |

## A.1.4 Machine directive

The frequency inverter itself is not a machine in the spirit of the EU machine directive. The start up of the frequency inverter in a machine is prohibited so long until it has been confirmed that the entire machine complies with the provisions of Directive 89/392/EWG (machine directive).

## A． 2 Instructions for UL and cUL

（Conforming standard UL 508C，CSA C22．2 No．14）

## A．2．1 Installation

The inverter FR－F 740 EC is UL－listed as a product for use in an enclosure．
Design an enclosure so that the inverter ambient temperature，humidity and atmosphere satisfy the specifications．（Refer to page 1）

## Wiring protection

For installation in the United States，branch circuit protection must be provided in accordance with the National Electrical Code and any applicable provincial codes．
For installation in Canada，branch circuit protection must be provided in accordance with the Canada Electrical Code and any applicable provincial codes．
Use the Class RK5 or Class T fuses certified by UL and cUL．

| FR－F740／746－ㅁㅁㅁㅁ－EC |  | 00023 | 00038 | 00052 | 00083 | 00126 | 00170 | 00250 | 00310 | 00380 | 00470 | 00620 | 00770 | 00930 | 01160 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated voltage［V］ |  | 480 V or more |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Rated current ［A］ | Without power factor improving reactor | 6 | 10 | 15 | 20 | 30 | 40 | 70 | 80 | 90 | 110 | 150 | 175 | 200 | 250 |
|  | With power factor improving reactor | 6 | 10 | 10 | 15 | 25 | 35 | 60 | 70 | 90 | 100 | 125 | 150 | 175 | 200 |


| FR－F 740－ロロロロロ－EC |  | 01800 | 02160 | 02600 | 03250 | 03610 | 04320 | 04810 | 05470 | 06100 | 06830 | 07700 | 08660 | 09620 | 10940 | 12120 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated voltage［V］ |  | 500 V or more |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Rated current ［A］ | Without power factor improving reactor | － | － | － | － | － | － | － | － | － | － | － | － | － | － | － |
|  | With power factor improving reactor | 300 | 350 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1350 | 1500 | 1800 | 2000 |

## A．2．2 Wiring of the power supply and motor

For wiring the input（R／L1，S／L2，T／L3）and output（ $\mathrm{U}, \mathrm{V}, \mathrm{W}$ ）terminals of the inverter，use the UL－listed copper wires（rated at $75^{\circ} \mathrm{C}$ ）and round crimping terminals．Crimp the crimping terminals with the crimping tool recommended by the terminal maker．

## A．2．3 Short circuit ratings

－ 01160 or less
Suitable for use in a circuit capable of delivering not more than 65 kA rms symmetrical amperes， 528 V maximum．
－ 01800 or more
Suitable for use in a circuit capable of delivering not more than 65 kA rms symmetrical amperes， 550 V maximum．

## A．2．4 Motor overload protection

When using the electronic thermal relay function as motor overload protection，set the rated motor current to Pr． 9 Electronic thermal O／L relay．
When connecting multiple motors to the inverter，install an external thermal relay individually．

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## AWARNING

- This is a personal computer dedicated CD ROM. Do not attempt to play it on ordinary audio devices. The loud volume may damage hearing and speakers.


## When playing the CD ROM on Windows OS

Operating enviroment
The following system is required to read instruction manuals contained in this CD ROM:

| Item |  |
| :---: | :--- |
| OS | Microsoft Windows 95 OSR 2.0, Windows 98 Second Edition, Windows Millenium Edition, Windows NT 4.0 with <br> Service Pack 6, Windows 2000 with Service Pack 2, Windows XP Professinal or Home Edition, Windows XP Tablet <br> PC Edition |
| CPU | Intel Pentium processor |
| Memory | 64MB of RAM |
| Hard disk | 24MB of available hard disk space |
| CD ROM drive | Double speed or more (more than quadruple speed is recommended) |
| Monitor | $800 \times 600$ dot or more |
| Application | Acrobat Reader 4.05 or more (This CD ROM contains Acrobat Reader 5.0. Install Acrobat Reader contained in the <br> CD ROM or download Acrobat Reader from the internet) |

Operating method of this CD ROM:

## - Acrobat Reader 5.0 installation procedure

(1) Start Windows and place this CD ROM in the CD ROM drive.
(2) If Acrobat Reader is not installed in your computer, an installation screen of Acrobat Reader is automatically displayed.
(3) Install according to the instruction of installation screen of Acrobat Reader.

Manual installation
(1) Start Windows and place this CD ROM in the CD ROM drive.
(2) Select a CD ROM drive (example: D drive) of "My computer" and click the right mouse button. Then, click "open" in the context menu.
(3) Open "WINDOWS" folder in "ACROBAT" folder in the opened folder and execute AR505ENU.EXE.
(4) Install according to the instruction of installation screen of Acrobat Reader.

- How to read instruction manual
(1) Start Windows and place this CD ROM in the CD ROM drive.
(2) "700 series documentation" PDF automatically opens.
(3) Click a PDF file name of the manual you want to read in the "INSTRUCTION MANUAL" list.
(4) PDF manual you clicked opens.

Manual opening of this CD ROM
(1) Start Windows and place this CD ROM in the CD ROM drive.
(2) Select a CD ROM drive (example: D drive) of "My computer" and click the right mouse button. Then, click "open" in the context menu.
(3) Open "INDEX.PDF" in the opened folder
(4) "700 series documentation" PDF opens. Operates according to the steps from Step (3) of "How to read instruction manual"

## When playing this CD ROM on Macintosh OS

| Item |  |
| :---: | :--- |
| OS | Mac OS 8.6, 9.0.4, 9.1, or Mac OS X* (* Some features may not be available.) |
| CPU | PowerPC processor |
| Memory | 64 MB of RAM |
| Hard disk | 24MB of available hard disk space |
| CD ROM drive | Double speed or more (more than quadruple speed is recommended) |
| Monitor | $800 \times 600$ dot or more |
| Application | Acrobat Reader 4.05 or more (This CD ROM contains Acrobat Reader 5.0. Install Acrobat Reader contained in the <br> CD ROM or download Acrobat Reader from the internet) |

- Operating method of this CD ROM
(1) Start Macintosh and place this CD ROM in the CD ROM drive.
(2) Double click on the CD ROM icon on the desk top to open the CD ROM.
(3) Open "MacOS" folder in "ACROBAT" folder in the opened folder and execute Acrobat Reader Installer.
(4) Install according to the instruction of installation screen of Acrobat Reader.
- How to read instruction manuals
(1) Start Macintosh and place this CD ROM in the CD ROM drive.
(2) Double click on the CD ROM icon on the desk top to open the CD ROM.
(3) Open "INDEX.PDF" in the opened folder
(4) "700 series documentation" PDF opens.
(5) Click a PDF file name of the manual you want to read in the "INSTRUCTION MANUAL" list.
(6) PDF manual you clicked opens.



[^0]:    *1 The setting depends on capacities. ( 01160 or less 01800 or more)
    *2 The setting depends on capacities. (00023/00038 to 00083/00126, 00170/00250 to 00770/00930, 01160/01800 or more)
    *3 The setting depends on capacities. (00170 or less/00250 or more)
    *4 The setting depends on capacities. ( 00170 or less/00250 to $01160 / 01800$ or more).

[^1]:    *1 The setting depends on capacities. (01160 or less/01800 or more)
    *2 Setting of " 9 " can be made for the 01800 or more.
    ${ }^{* 3}$ Setting can be made for the 01800 or more.
    *4 Setting of "100 to 103 ", "114 to 117 " can be made for the 01800 or more.

[^2]:    *1 Setting of "9" can be made for the 01800 or more.

[^3]:    *1 Setting of "7, 107" can be made for the 01800 or more.

[^4]:    *1 The setting depends on capacities. (01160 or less/01800 or more)

[^5]:    *1 The setting depends on capacities. (01160 or less/01800 or more)

